Course code	Course Name	L-T-P - Credits	Year of Introduction
EE303	Linear Control Systems	2-1-0-3	2016

Prerequisite: Nil

Course Objectives:

- To provide a strong foundation on the analytical and design techniques on classical control theory and modelling of dynamic systems

Syllabus :

Open loop-and closed loop control systems- Transfer function - Control system components-Steady stare error- static error coefficient- dynamic error coefficient-Stability Analysis- Root locus- Frequency domain analysis-Bode plot-polar plot-Nyquist stability criterion- Non-minimum phase system - transportation lag.

Expected outcome.

The students will have the ability to

i. develop mathematical models of various systems.
ii. analyse the stability aspects of linear time invariant systems.

Text Books:

1) Dorf R. C. and R. H. Bishop, Modern Control Systems, Pearson Education, 2011.
2) Nagarath I. J. and Gopal M., Control System Engineering, Wiley Eastern, 2008.
3) Nise N. S., Control Systems Engineering, 6/e, Wiley Eastern, 2010.
4) Ogata K., Modern Control Engineering, Prentice Hall of India, New Delhi, 2010.

References:

1) Gibson J. E., F. B. Tuteur and J. R. Ragazzini, Control System Components, Tata McGraw Hill, 2013
2) Gopal M., Control Systems Principles and Design, Tata McGraw Hill, 2008.
3) Imthias Ahamed T P, *Control Systems*, Phasor Books, 2016
4) Kuo B. C., Automatic Control Systems, Prentice Hall of India, New Delhi, 2002.

Course Plan

Module	Contents	Hours	Sem. Exam Marks
I	Open loop-and closed loop control systems: Transfer function of LTI systems-Mechanical and Electromechanical systems – Force voltage and force current analogy - block diagram representation - block diagram reduction - signal flow graph - Mason's gain formula - characteristic equation.	8	15%
II	Control system components: DC and AC servo motors – synchro - gyroscope - stepper motor - Tacho generator. Time domain analysis of control systems: Transient and steady state responses - time domain specifications - first and second order systems - step responses of first and second order systems.	6	15%
	FIRST INTERNAL EXAMINATION		
III	Error analysis - steady state error analysis - static error coefficient of type 0,1, 2 systems - Dynamic error coefficients. Concept of stability: Time response for various pole locations - stability of feedback system - Routh's stability criterion	7	15%
IV	Root locus - General rules for constructing Root loci – stability from root loci - effect of addition of poles and zeros.	7	15%
	SECOND INTERNAL EXAMINATION		
V	Frequency domain analysis: Frequency domain specifications- Analysis based on Bode plot - Log magnitude vs. phase plot,	7	20%

VI	Polar plot- Nyquist stability criterion-Nichols chart - Non-minimum phase system - transportation lag.	7	20%
END SEMESTER EXAM			

QUESTION PAPER PATTERN:

Maximum Marks: 100 Exam Duration: 3Hourrs.

Part A: 8 compulsory questions.

One question from each module of Modules I - IV; and two each from Module V & VI.

Student has to answer all questions. (8 x5)=40

Part B: 3 questions uniformly covering Modules I & II. Student has to answer any 2 from the 3 questions: (2 x 10) =20. Each question can have maximum of 4 sub questions (a,b,c,d), if needed.

Part C: 3 questions uniformly covering Modules III & IV. Student has to answer any 2 from the 3 questions: (2 x 10) =20. Each question can have maximum of 4 sub questions (a,b,c,d), if needed.

Part D: 3 questions uniformly covering Modules V & VI. Student has to answer any 2 from the 3 questions: (2 x 10) =20. Each question can have maximum of 4 sub questions (a,b,c,d), if needed.